

Numerical modelling as defined in Encyclopædia Britannica:

*“A computer-generated description of a mathematical system to represent the behaviour of a real or proposed system that uses a set of equations and inequalities to represent the functional relationships within the system.”*

# Numerical modelling of ice & ice-structure interactions



KIVI NIRIA

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34<sup>e</sup> lustrum  
170 jaar TU Delft

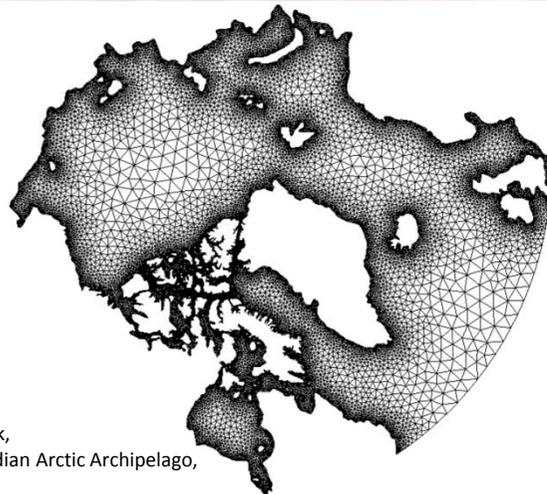
## Arctic Battle

Symposium - 8 March 2012

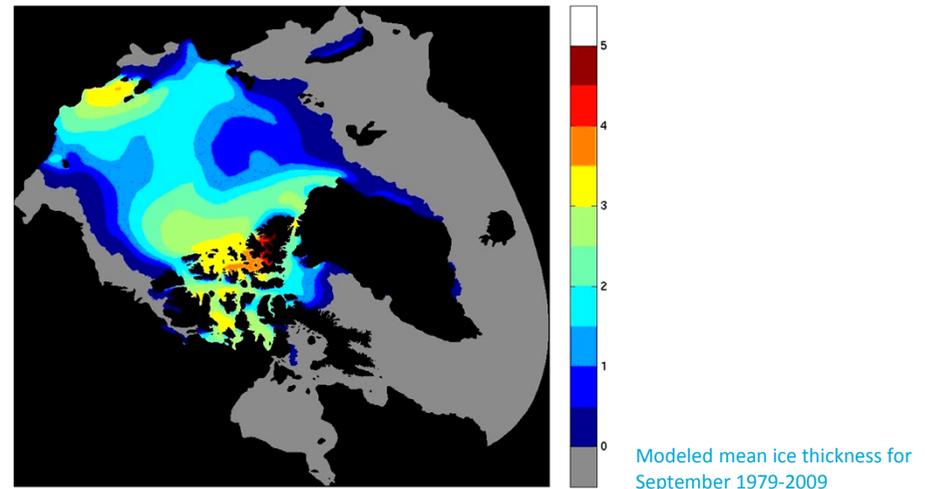
# Current uses for numerical modelling

Numerical modelling is widely used for applications in Arctic Engineering:

- Flow of ice sheets
- Thermodynamic growth & decay of ice
- Response of sea ice to climate variations
- Ice concentrations
- Oceanography



Terwisscha van Scheltinga, Myers & Pietrzak,  
A finite element sea ice model of the Canadian Arctic Archipelago,  
Ocean Dynamics 60, 1539-1558, 2010



Arctic Battle Symposium - Friday, 09 March 2012

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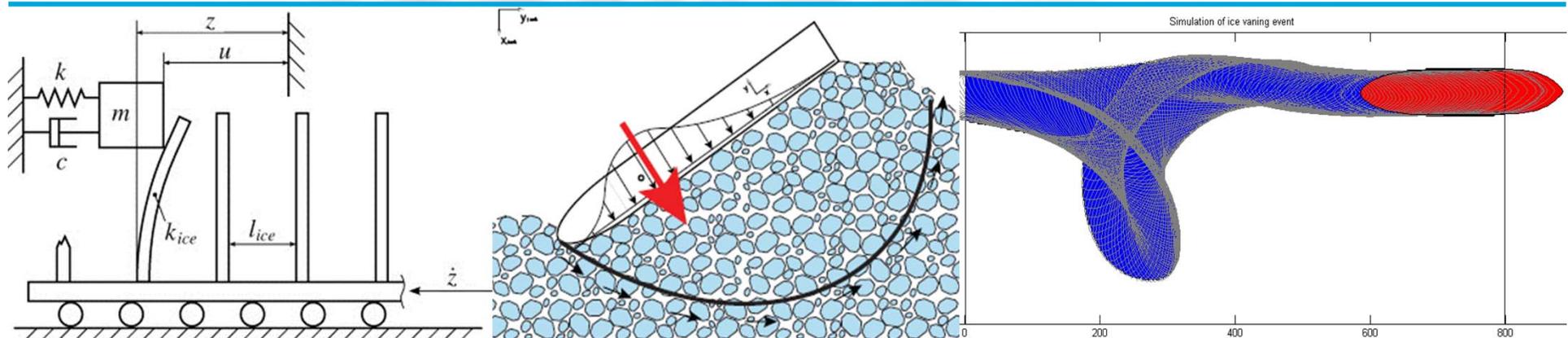
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# Numerical applications for ice-structure interaction

Current and past numerical modelling for ice-structure interaction:

- Phenomenological modelling of dynamic ice-structure interaction, by: Kärnä - VTT Finland / Huang & Liu - CAS China
- Ice-structure interaction between ships and broken ice, by: Sayed, Frederking & Barker - NRC Canada / Løset - NTNU Norway
- 'Simplistic' ice-structure interaction models based on static ice loads from ISO19906 combined with Ansys, by: Hidding & Bonnafoux, MSc. DUT/SBM



# Our purpose for numerical modelling

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We are however interested in:

- The behaviour of ice when its loaded
- The way ice fails against different types of structures, and thus
- The loads that ice sheets or ice floes exert on offshore structures

Our focus is the interaction of offshore structures with **first-year level ice**, because:

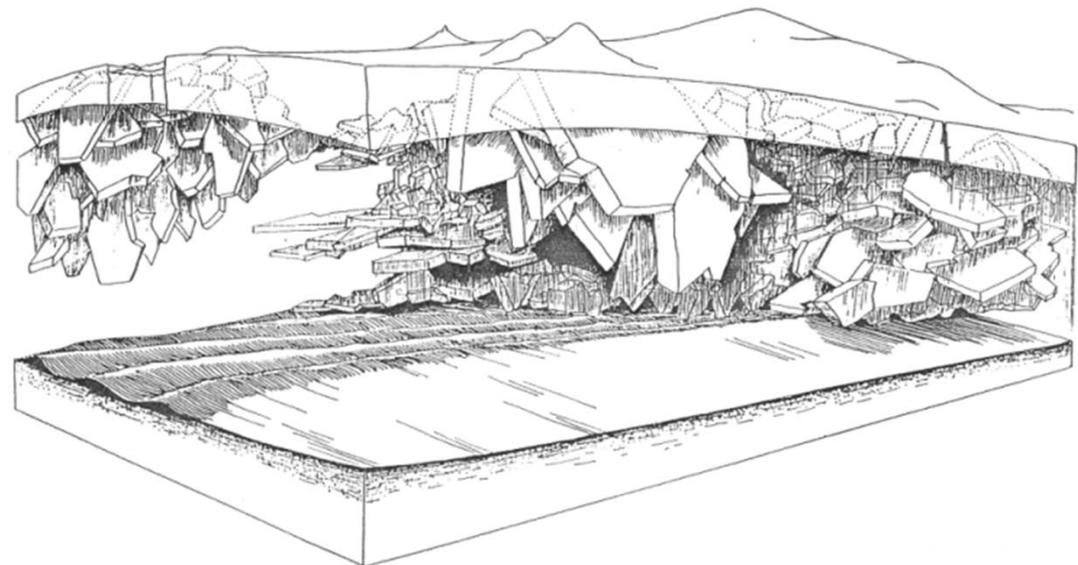
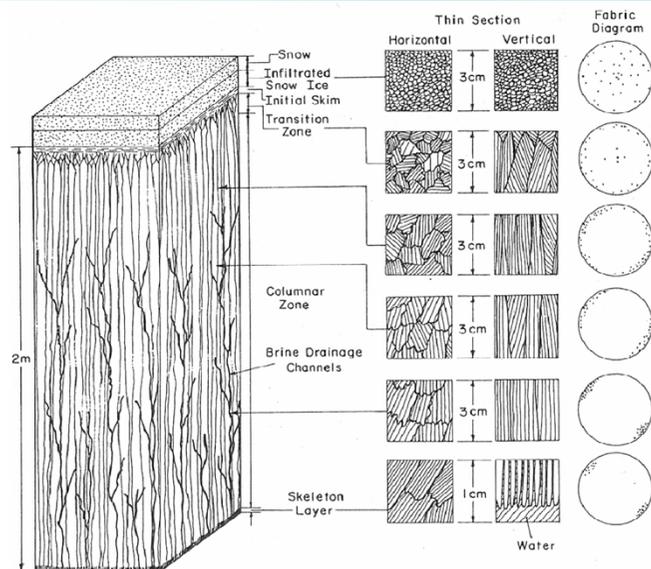
- Loads due to level ice floes are normative over those due to broken ice fields
- It is the most common ice feature at locations considered for development

Thus, for now, **neglecting** the critical ice loads due to for example ice ridges or icebergs



# Typical properties of ice

- Ice is a heterogeneous natural material
- Ice is anisotropic
- Ice has a variable shape that is unknown and therefore uncertain
- Ice-structure interactions are large scale → scaled model tests



# Model-scale versus full-scale tests

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At first, from scaled model tests:

*“Failure of sea ice was thought to be well-described by **plastic limit analysis**”*

(Plastic limit analysis = Linear elasticity until the critical stress is reached, then yield until total failure)

But when some full-scale data became available, it was found that:

*“The measured forces exerted by moving ice on an oil platform may be **an order of magnitude smaller** than the predictions based on laboratory tests!”*

This is due to the size effect on structural strength:

- Statistical size effect
- Energetic (or deterministic) size effect

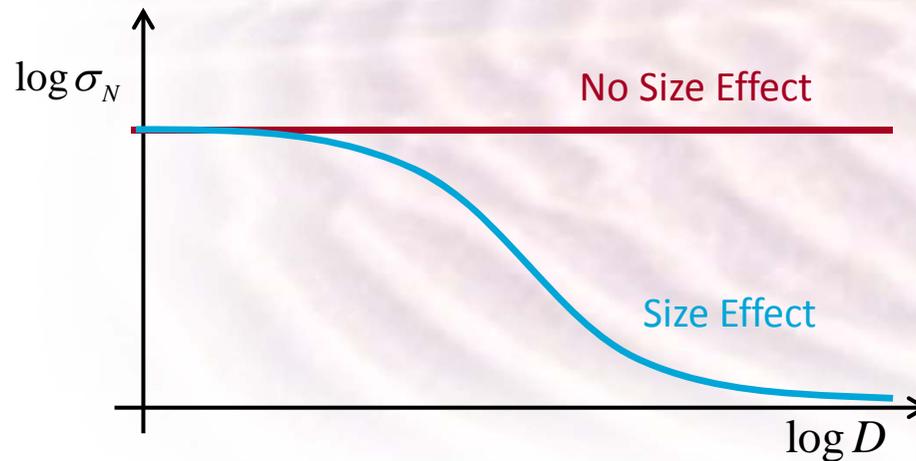
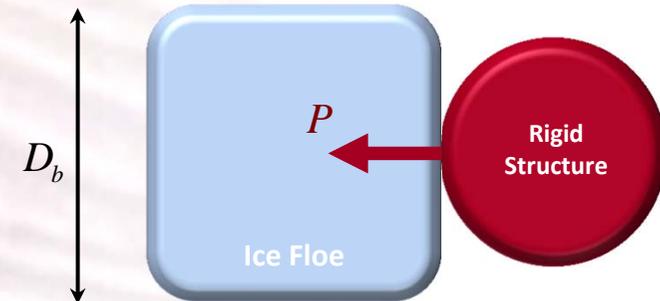
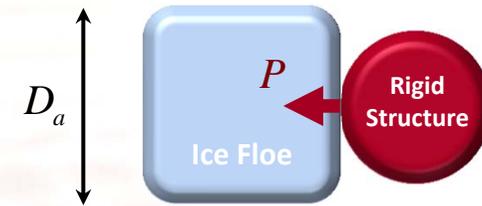


# The principle of size effect

No Size Effect:  $\frac{\sigma_N^a}{\sigma_N^b} = \frac{f(D_a^2)}{f(D_b^2)} = f\left(\frac{D_a^2}{D_b^2}\right)$

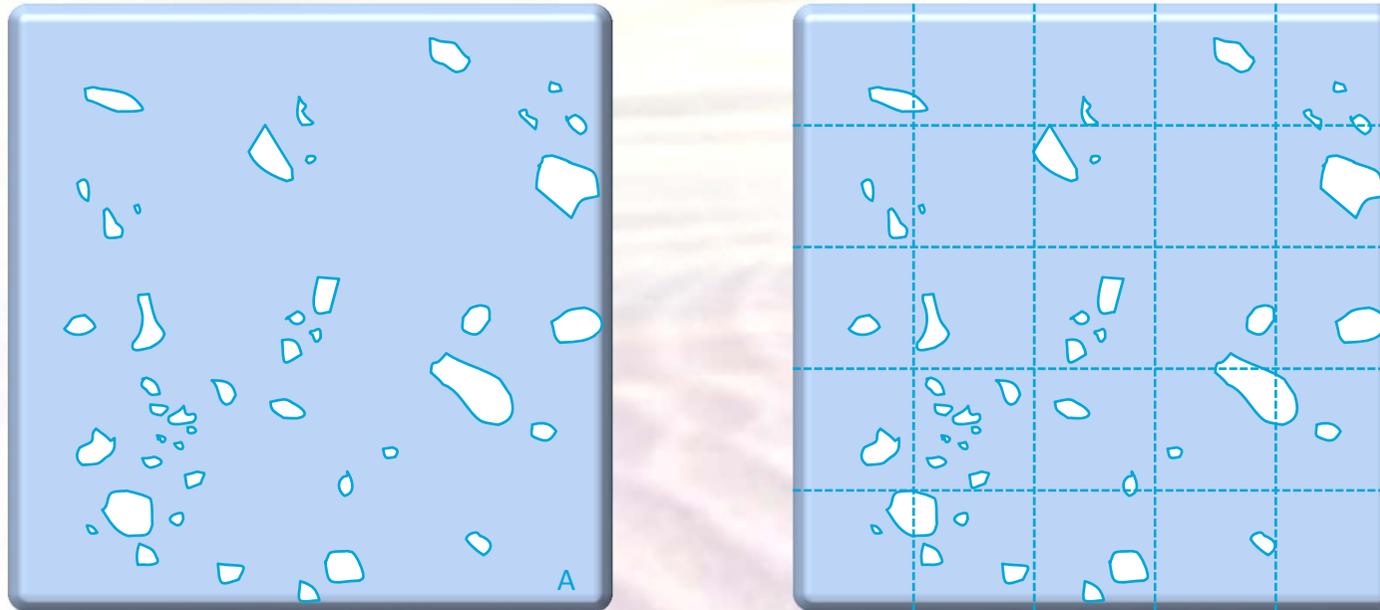
Size Effect:  $\frac{\sigma_N^a}{\sigma_N^b} = \frac{f(D_a^2)}{f(D_b^2)} \neq f\left(\frac{D_a^2}{D_b^2}\right)$

Nominal strength:  $\sigma_N = C_\sigma \frac{P}{D^2}$



# Statistical size effect

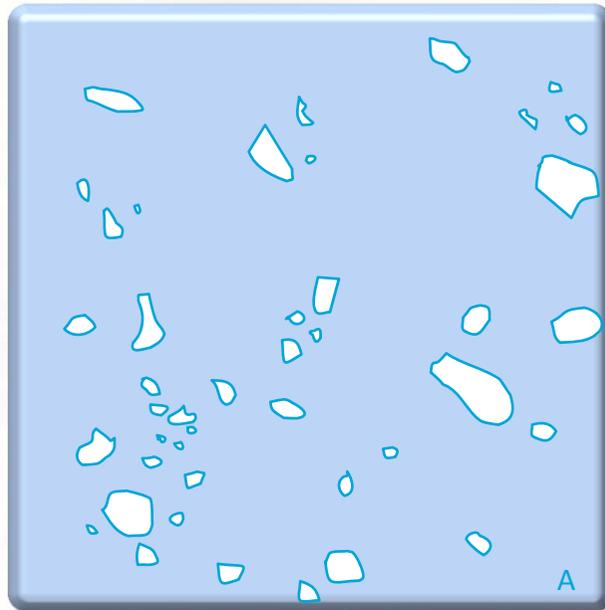
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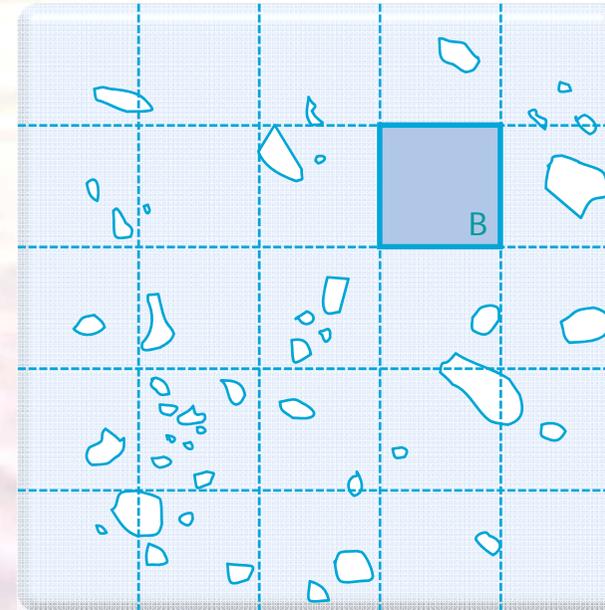
The average of the nominal strength of all specimen in floe A is the same as the nominal strength of floe A



# Statistical size effect



Scale B up to the size of A



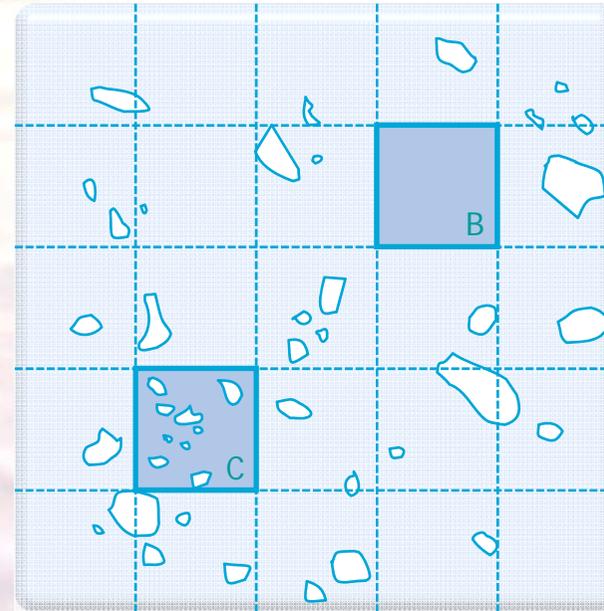
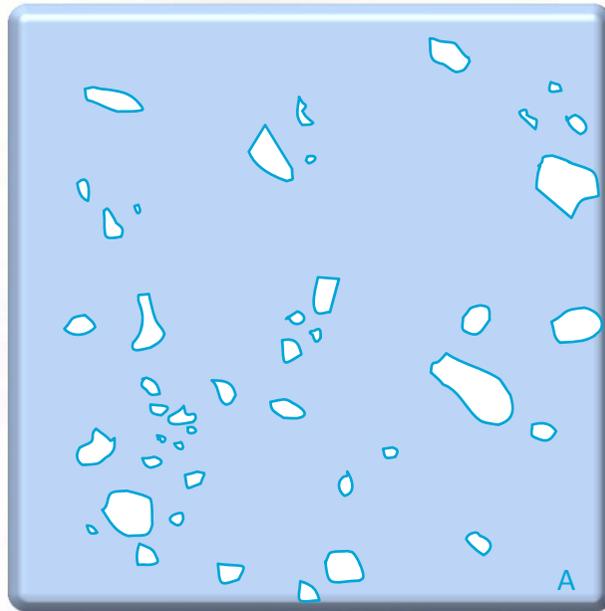
Floe B is much stronger than floe A:

$$\sigma_N^A < \sigma_N^B$$



# Statistical size effect

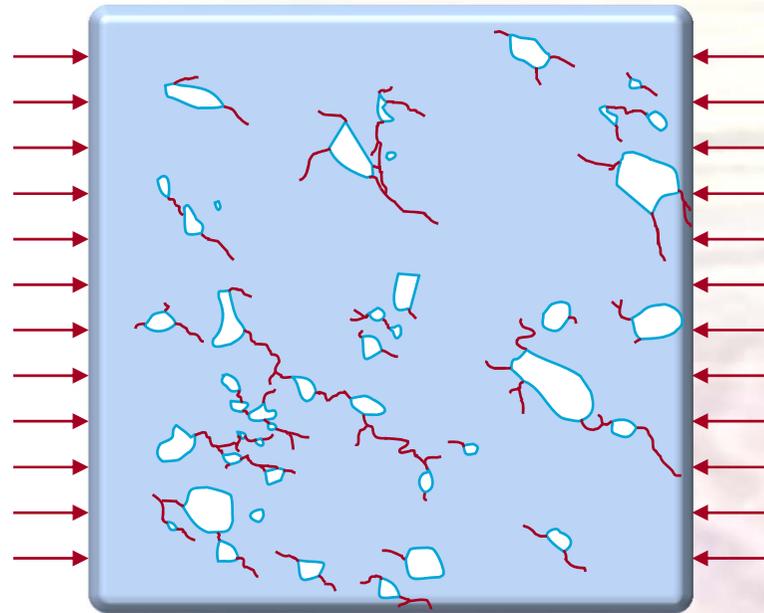
Ice floe A will not fail at specimen B, but for example at specimen C!



- An ice floe is as strong as its **weakest link**
- The bigger the floe, the higher the chance on a relatively weak spot



# Energetic size effect



- When loaded, tiny cracks appear at weak spots in the ice
- Under continuous loading, these cracks propagate due to peak stresses at the crack tip and stress relief in the surrounding ice, i.e. **stress redistribution**
- The strength of an ice floe then depends on the energy dissipation due to crack propagation, which is **independent** of the floe size.

In large ice floes, crack propagation occurs at relatively lower stresses than crack propagation in small ice floes.



# Influence size effect on ice-failure

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So generally, we can state that:

*“The nominal strength of ice decreases relative to the floe size”*

Due to the size effect, ice can be considered a quasi-brittle material:

- Small ice floes interacting with small structures:  
*Macro-failure in a more **ductile** manner due to distributed micro-cracking*
- Large ice floes interacting with large structures:  
*Macro-failure in an almost perfect **brittle** manner*

Also **the relative velocity** between an ice floe and a structure influences the way an ice floe fails during ice-structure interaction:

- Low velocities  $\longrightarrow$  ductile
- High velocities  $\longrightarrow$  brittle



# Preferred practice due to the size effect

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1. Create a numerical model that:
  - captures the desired phenomena, and
  - includes the size effect
2. Perform scale-model tests
3. Tune the parameters of the numerical model to the scale-model tests
4. Use the resulting numerical model to obtain results for full-scale situations

This is known as: “*Numerical Upscaling*”



# Numerical approaches

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The choice of the model and thus the numerical approach to be used, mainly depends on the scale of the phenomena one wishes to capture

The different scales are:

- Macro → Global phenomena
- **Meso → Local phenomena**
- Micro → Microstructure phenomena
- Nano → Molecular phenomena

Macro-scale modelling for global phenomena:

- Continuum models can sometimes be (partially) solved analytically
- Numerically solving these models requires relatively short calculation time
- Continuum models do not capture all properties of an ice floe

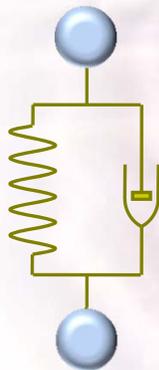


# Meso-scale modelling: the hexagonal lattice

- The ice floe is modelled as a hexagonal system of rigid particles
- Other geometrical configurations of the particles can be made
- The interaction between any 2 adjacent particles is described by kinematic elements that may have various properties:



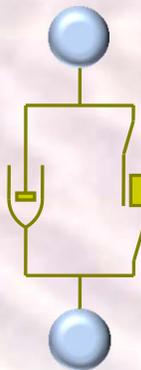
Hooke



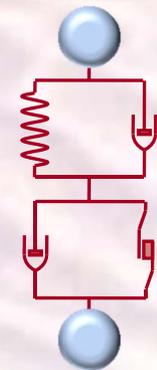
Kelvin-Voigt



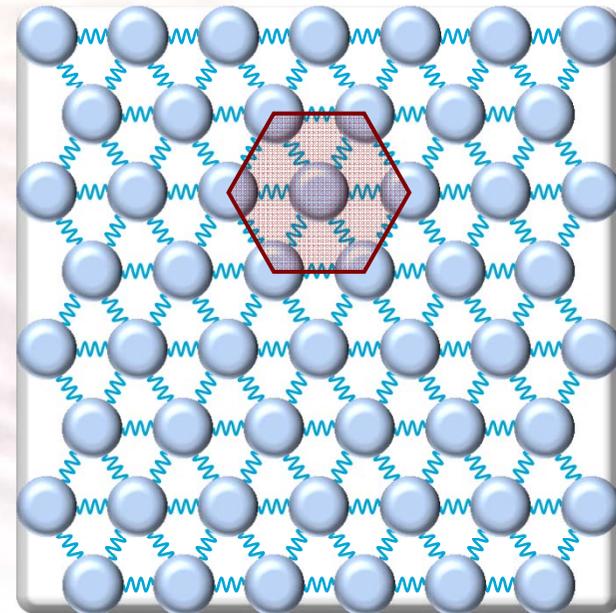
Prandtl



Bingham



Bingham-Kelvin-Voigt



# A hexagonal lattice with Kelvin-Voigt elements

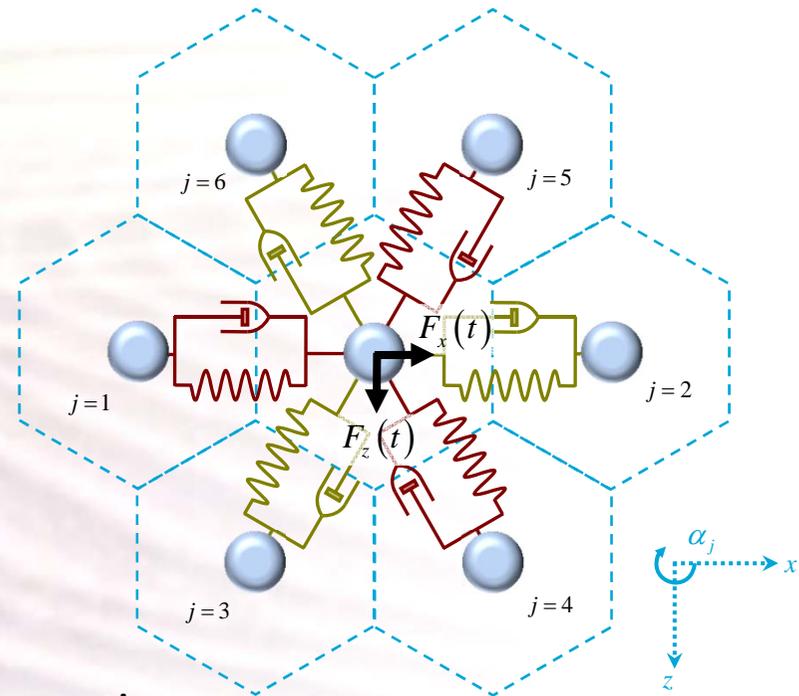
- At every node in the lattice, we have 2 equations of motion, respectively describing the equilibria in x- and z-direction:

$$M\ddot{u}_x - \hat{K}_e \sum_{j=1}^6 e_j \cos \alpha_j = F_x(t)$$

$$M\ddot{u}_z - \hat{K}_e \sum_{j=1}^6 e_j \sin \alpha_j = F_z(t)$$



$$\underline{\underline{M}}\ddot{\underline{\underline{u}}} + \underline{\underline{C}}\dot{\underline{\underline{u}}} + \underline{\underline{K}}\underline{\underline{u}} = \underline{\underline{F}}(t)$$

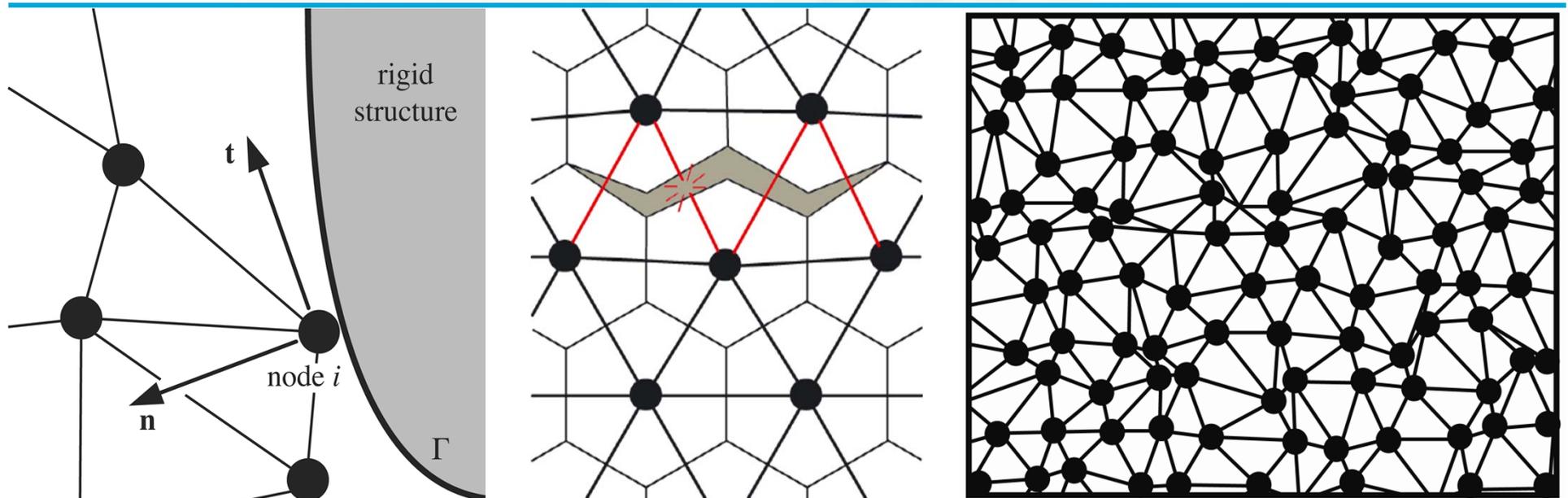


- The properties of the particles and the kinematic elements may be varied, enabling inhomogeneity



# Crack propagation in the lattice

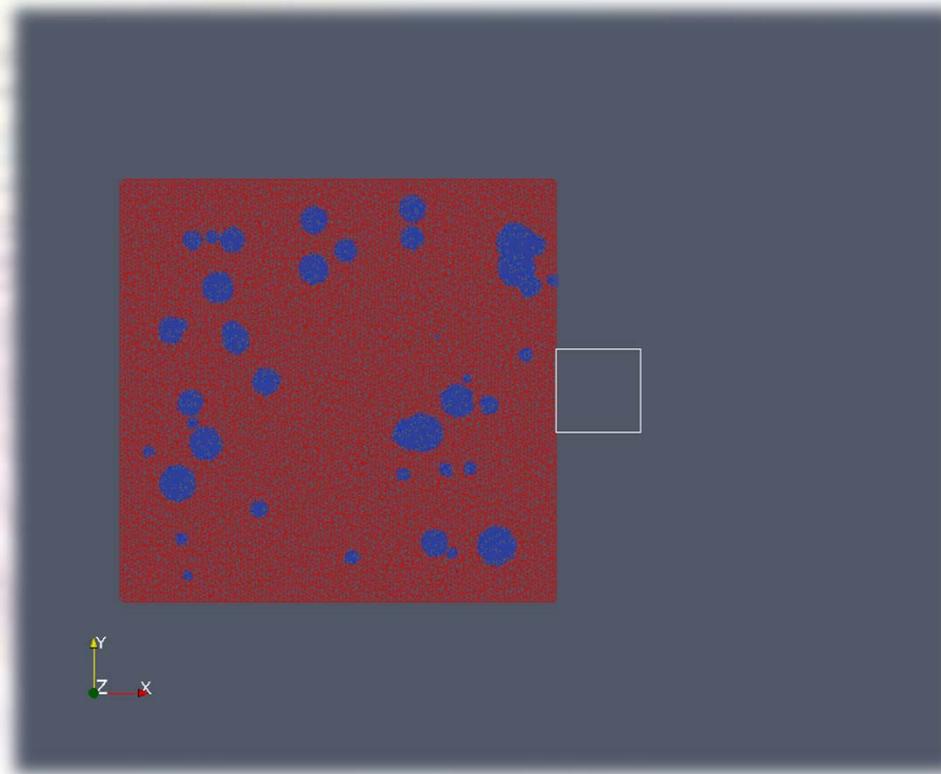
- When the force in an element between 2 adjacent nodes becomes too large, a crack appears and that element is deleted
- Using a regular mesh, crack propagation is mesh dependent, therefore the mesh is randomized



# Ice crushing against a rigid structure

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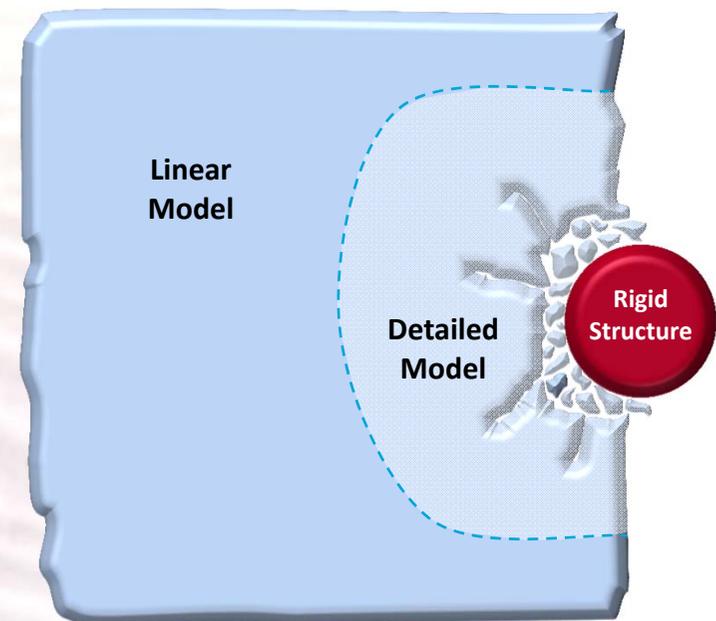
- A lattice model to simulate ice crushing against a rigid structure, by:  
Dr. O. Dorival and Prof. A. Metrikine (2008)



# Perspective: A coupled discrete-continuous model

With the aim to **improve usability** and to **limit calculation time**, we divide the floe into 2 segments:

- The part of the ice floe close to the ice-structure interaction is modelled with **high detail** using the discrete lattice to account for the nonlinear behaviour of the ice
- At a distance from the ice-structure interaction, the behaviour of the ice floe is linear and thus modelled as a **linear continuum**
- We then couple the discrete lattice and the continuum such that the wave reflection at the lattice-continuum interface is minimal



# A non-reflective lattice-continuum interface

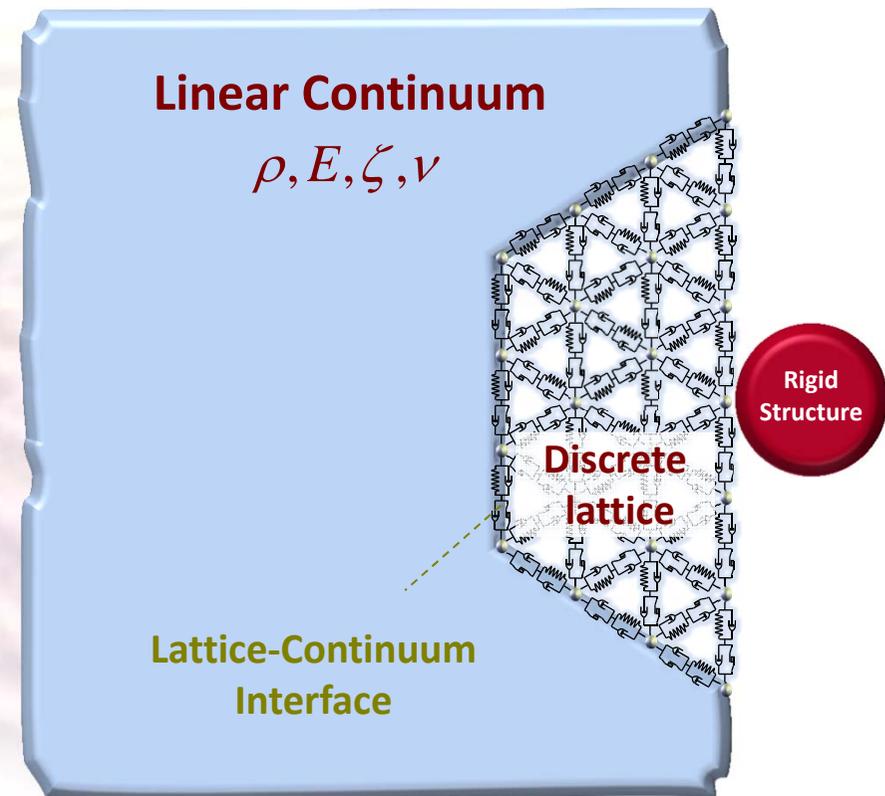
Dynamic stiffness is “*The ratio between a dynamic load and its response*”

The dynamic stiffness is described by the **force-displacement** relation in the frequency domain as:

$$F(\omega) = \chi(\omega)u(\omega)$$

The force-displacement relation in the time domain is then found applying the **inverse Laplace transform**, and is found as the convolution of  $\chi(t)$  and  $u(t)$ :

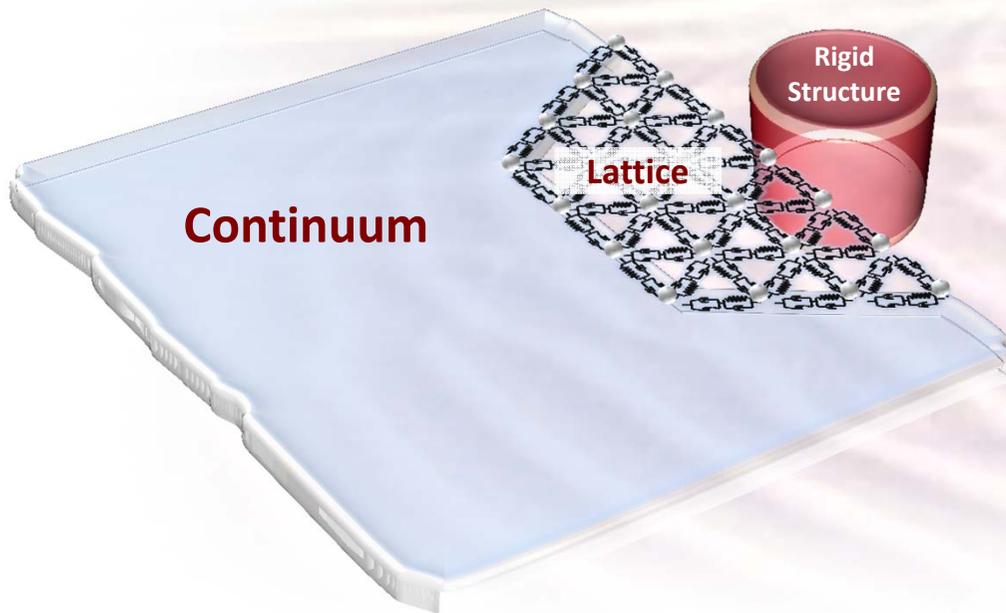
$$F(t) = \int_0^t \chi(t-\tau)u(\tau)d\tau$$



# Perspective: Extension into 3D

Extending the model into 3D by adding the vertical dimension allows for:

- Clearance of rubble under the ice sheet
- The option to model the bending of an ice floe against a conical structure



Hydralab IV – HyIII-HSVA-04 – Kärnä et al.



# Numerical modelling of ice-structure interaction

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- The models that can be studied **analytically** often do not capture the phenomena that are observed in reality during ice-structure interaction
- Scale model tests give insight in the **phenomena** of ice-structure interaction but can not be scaled straightforwardly to actual size problems
- To obtain a better description and **understanding** of ice and ice-structure interaction, it is a necessity to model these phenomena numerically
- Additionally, numerical models are preferred over model- and full-scale tests for **cost effective design**





Thank you!

